Interest Points:
A - LowerLeftSnout$_3$
B - LowerRightSnout$_3$
C - UpperLeftSnout$_3$
D - UpperRightSnout$_3$
E - LeftMicrophone$_3$
F - RightMicrophone$_3$
G - AntennaBase$_3$
H - AntennaTip$_3$
I - HeadLight$_3$

ERS-220 Head

<table>
<thead>
<tr>
<th></th>
<th>$\Delta x$</th>
<th>$\Delta y$</th>
<th>$\Delta z$</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. - tilt$_0$</td>
<td>75</td>
<td>0</td>
<td>50</td>
</tr>
<tr>
<td>2. - pan$_1$</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>3. - nod$_2$</td>
<td>0</td>
<td>0</td>
<td>48</td>
</tr>
<tr>
<td>IR. - camera$_3$</td>
<td>0</td>
<td>0</td>
<td>66.6</td>
</tr>
<tr>
<td>7.036</td>
<td>-14.595</td>
<td>26.5</td>
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</tbody>
</table>

The IR beam angles and sensor position are measured from calibration on ERS-210s, and may have some small variation between AIBOs.